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Adversarial Examples for Semantic Segmentation and Object Detection

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Outline

- Introduction
- Adversarial Examples in Computer Vision
- Dense Adversarial Generation (DAG)
- Experiments: White-box Attack
- Experiments: Black-box Attack
- Fancy Examples
- Conclusions and Future Work

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Introduction

- Deep Learning
 - The state-of-the-art machine learning theory
 - Using a cascade of many layers of non-linear neurons for feature extraction and transformation
 - Learning multiple levels of feature representation
 - Higher-level features are derived from lower-level features to form a hierarchical architecture
 - Multiple levels of representation correspond to different levels of abstraction

Introduction (cont.)

- The Convolutional Neural Networks
 - A fundamental machine learning tool
 - Good performance in a wide range of problems in computer vision as well as other research areas
 - Evolutions in many real-world applications
 - Theory: a multi-layer, hierarchical network often has a larger capacity, also requires a larger amount of data to get trained

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Adversarial Examples: Introduction

- What is an adversarial example (in this work)?
 - An image, with a small perturbation added, which can still be recognized by humans, but not by the computers (*deep neural networks*)
 - Type 1: an image with clear visual contents is recognized incorrectly
 - Type 2: an image with no visual contents is recognized as a non-understandable class

Adversarial Examples: Type 1

- Slightly perturbed natural images that are completely wrongly recognized
 - Example from [Goodfellow, ICLR'15]



Adversarial Examples: Type 2

- Meaningless patterns that are recognized as object classes with a very high confidence
 - Examples from[Nguyen, CVPR'14]



Previous Work

- Generating adversarial examples
 - Steepest gradient descent [Szegedy, ICLR'14], gradient sign [Goodfellow, ICLR'15], universal adversarial attack [M-Dezfooli, CVPR'17], etc.
- Defending adversarial examples
 - Distillation [Papernot, IEEE-SSP'16], large-scale learning [Kukarin, ICLR'17], ensemble [Tramer, arXiv'17], detection [Metzen, ICLR'17], randomization [Xie, arXiv'17], etc.

Why Adversaries Exist?

- Opinion 1: deep networks are too complicated so that the high-dimensional space contains many non-linear or unexplainable structures, or they are too sensitive to small noise
- Opinion 2: deep networks are still too simple to defend these malignant attacks
- Opinion 3: deep networks are not the model we want!

Our Contribution

- We extend the adversarial examples to both semantic segmentation and object detection

 We are the first to achieve this goal systematically
- We evaluated both *white-box* attack and *black-box* attack tasks
 - White-box: the network parameters are known
 - Black-box: the network parameters are unknown (transferring the adversarial perturbations)

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Some Typical Results



Original Image



Original Segmentation



Original Detection



Added Perturbation (10x)



Attacked Segmentation



Attacked Detection

Formulation: Optimization Goal

- Let a deep network be $\mathbf{f}(\mathbf{X}; \mathbf{\Theta}) \in \mathbb{R}^{C}$
 - X: input region, Θ : weights (fixed), C: # of classes
- Goal: modifying **X** to make wrong prediction
- Optimization *target*: the basic unit
 - For classification: the entire image (previous work)
 - What about segmentation?
 - What about detection?

Formulation: Optimization Goal

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- Goal: modifying **X** to make wrong prediction
- Optimization *target*: the basic unit
 - For classification: the entire image (previous work)
 - For segmentation: all pixels in the image
 - For detection: densely distributed bounding boxes

Dense Adversarial Generation

- A white-box attack
 - Image and network dependent
- Flowchart
 - Defining the active set
 - Gradient descent
 - Until convergence

Algorithm 1: Dense Adversary Generation (DAG) **Input** : input image X; the classifier $\mathbf{f}(\cdot, \cdot) \in \mathbb{R}^C$; the target set $\mathcal{T} = \{t_1, t_2, \ldots, t_N\};$ the original label set $\mathcal{L} = \{l_1, l_2, \dots, l_N\};$ the adversarial label set $\mathcal{L}' = \{l'_1, l'_2, \dots, l'_N\};$ the maximal iterations M_0 : **Output:** the adversarial perturbation r; 1 $\mathbf{X}_0 \leftarrow \mathbf{X}, \mathbf{r} \leftarrow \mathbf{0}, m \leftarrow \mathbf{0}, \mathcal{T}_0 \leftarrow \mathcal{T};$ 2 while $m < M_0$ and $\mathcal{T}_m \neq \emptyset$ do $\mathcal{T}_m = \{t_n \mid \arg\max_c \{f_c(\mathbf{X}_m, t_n)\} = l_n\};$ 3 4 $\mathbf{r}_m \leftarrow$ $\sum_{t_n \in \mathcal{T}_m} \left[\nabla_{\mathbf{X}_m} f_{l'_n}(\mathbf{X}_m, t_n) - \nabla_{\mathbf{X}_m} f_{l_n}(\mathbf{X}_m, t_n) \right];$ $\mathbf{r}'_m \leftarrow \frac{\gamma}{\|\mathbf{r}_m\|_{\infty}} \mathbf{r}_m;$ 5 6 $\mathbf{r} \leftarrow \mathbf{r} + \mathbf{r}'_m;$ $\mathbf{X}_{m+1} \leftarrow \mathbf{X}_m + \mathbf{r}'_m; \\ m \leftarrow m+1;$ 9 end Return: r

Comments on Object Detection

- We attacked a type of frameworks, which first extract a number of proposals, then assign a class label for each proposal
- A possibility: the adversarial perturbation changes the set of proposals, and our attack will not work on the new proposals
 - That is why we need to generate *dense* bounding boxes (see the next page)

Diagnosis: Denseness

- Denseness: the number of generated boxes in object detection task (the more the better)
 - Controlled by the non-maximum-suppression



Diagnosis: Convergence

- Convergence is mostly guaranteed
 - Failed to converge in a fixed # of rounds: < 1%
 - Even in these cases, generated perturbations work well



Diagnosis: Perceptibility

• Low intensity of adversarial perturbations

• Perceptibility:
$$p = \left(\frac{1}{K}\sum_{k} \|\mathbf{r}_{k}\|_{2}^{2}\right)^{1/2}$$

-K: # of image pixels

 $-\mathbf{r}_k$: RGB vector of perturbation ([0,1]-normalized)

• Typical value of p is $[1.0,3.0] \times 10^{-3}$

Some Typical Results



Original Image



Original Segmentation



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White-Box Attack: Definition

- Given an image X and a network f(X; Θ) in which the structure and weights are known
 - This is the same setting as in the algorithm
 - Adversarial examples are easily generated, given that our algorithm converges (mostly guaranteed)

White-Box Attack: Results

- Semantic segmentation part
 - FCN and DeepLab were evaluated
 - Bold numbers indicate white-box attacks

Adversarial	ECN Alox	FCN Alox*	FCN VCC	FCN VCC*	DL VCC	DI RN101
Perturbations from	r CIN-Alex	r CN-Alex	101-100	FCR-766	DL-100	DL-KNI01
None	48.04	48.92	65.49	67.09	70.72	76.11
FCN-Alex (r ₅)	3.98	7.94	64.82	66.54	70.18	75.45
FCN-Alex* (r_6)	5.10	3.98	64.60	66.36	69.98	75.52
FCN-VGG (r ₇)	46.21	47.38	4.09	16.36	45.16	73.98
FCN-VGG* (r ₈)	46.10	47.21	12.72	4.18	46.33	73.76
$r_5 + r_7$	4.83	8.55	4.23	17.59	43.95	73.26
$\mathbf{r}_5 + \mathbf{r}_7$ (permuted)	48.03	48.90	65.47	67.09	70.69	76.04
$r_6 + r_8$	5.52	4.23	13.89	4.98	44.18	73.01
$\mathbf{r}_6 + \mathbf{r}_8$ (permuted)	48.03	48.90	65.47	67.05	70.69	76.05

White-Box Attack: Results

- Object recognition part
 - Faster-RCNN and R-FCN were evaluated
 - Bold numbers indicate white-box attacks

Adversarial	EP 7E 07	FP 7F 0712	FP VCC 07	FR-VGG-	R-FCN-	R-FCN-
Perturbations from	FR-21-07	FK-ZF-0/12	FK-V66-07	0712	RN50	RN101
None	58.70	61.07	69.14	72.07	76.40	78.06
FR-ZF-07 (r ₁)	3.61	22.15	66.01	69.47	74.01	75.87
FR-ZF-0712 (r ₂)	13.14	1.95	64.61	68.17	72.29	74.68
FR-VGG-07 (r ₃)	56.41	59.31	5.92	48.05	72.84	74.79
FR-VGG-0712 (r ₄)	56.09	58.58	31.84	3.36	70.55	72.78
$r_1 + r_3$	3.98	21.63	7.00	44.14	68.89	71.56
$\mathbf{r}_1 + \mathbf{r}_3$ (permuted)	58.30	61.08	68.63	71.82	76.34	77.71
$\mathbf{r}_2 + \mathbf{r}_4$	13.15	2.13	28.92	4.28	63.93	67.25
$\mathbf{r}_2 + \mathbf{r}_4$ (permuted)	58.51	61.09	68.68	71.78	76.23	77.71

White-Box Attack: Examples



Original Image

Added Perturbation (10x)

Attacked Segmentation



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Black-Box Attack: Definition

- Given an image X and a network f(X; Θ) in which the structure and weights are *unknown*
 - It is even possible that the task is unknown
 - This setting is much more challenging
 - The difficulty goes up with the difference between the source network (the white box) and the target network (the black box)

Black-Box Attack: Results

- Semantic segmentation part
 - Transfer across different training sets
 - Transfer across different networks

Adversarial	ECN Alox	FCN Alox*	FCN VCC	FCN VCC*	DL VCC	DI RN101
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Black-Box Attack: Results

- Object recognition part
 - Transfer across different training sets
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Black-Box Attack: Results

- Transfer across different tasks
 - This is the most challenging task investigated
 - Ensemble is the only way of enhancing attack

Adversarial	FP 7F 07	FR VCC 07	ECN Alox	FCN VCC	P ECN PN101
Perturbations from	FK-ZF-0/	FK-V66-0/	r CIN-Alex	ren-vee	K-FCN-KNIUI
None	56.83	68.88	35.73	54.87	80.20
FR-ZF-07 (r ₁)	5.14	66.63	31.74	51.94	76.00
FR-VGG-07 (r ₃)	54.96	7.17	34.53	43.06	74.50
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FCN-VGG (r ₇)	55.24	56.33	33.99	4.10	73.86
$r_1 + r_3 + r_5$	5.02	8.75	4.32	37.90	69.07
$r_1 + r_3 + r_7$	5.15	5.63	28.48	4.81	65.23
$r_1 + r_5 + r_7$	5.14	47.52	4.37	5.20	68.51
$r_3 + r_5 + r_7$	53.34	5.94	4.41	4.68	67.57
$r_1 + r_3 + r_5 + r_7$	5.05	5.89	4.51	5.09	64.52

Black-Box Attack: Facts

- Black-box attack is much more difficult
 - The difficulty goes up with the difference between the source and target networks
- "Difficulty levels" in transfer
 - Level 1: across different datasets
 - Level 2: across different network structures
 - Shallower networks are not easier to attack
 - Level 3: across different vision tasks
 - Same network structure makes things easier

Black-Box Attack: Examples

Original Image

Original Result from Network 2

Network 1: FR-ZF-0712 Network 2: FR-VGG-07

Network 1: FCN-VGG Network 2: DL-VGG

Network 1: FCN-VGG Network 2: FR-VGG-07

Network 1: FR-VGG-07 Network 2: FCN-VGG













Adversarial Result from Network 1









Adversarial Result from Network 2









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Different Geometric Patterns



Cow

Sheep

Dining-Table

Sofa

Chair

Potted-Plant

Cat

Person

10/	11	/20	17
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Car

Motorbike

Horse

TV/Monitor

Dog

Train

An adversarial example for both detection and segmentation



The top row shows FR-VGG-07 and FR-ZF-07 detection results, and the bottom row shows FCN-Alex and FCN-VGG segmentation results. The blue in segmentation results corresponds to boat.

Same adversarial example, Completely different Outputs



We add one adversarial perturbation (magnified by 10) to the same original image to generate different prespecified segmentation masks on two deep segmentation networks (FCN-Alex and FCN-VGG). This is a more difficult task compared to that shown in previous figure, where two different adversarial perturbations are used to generate two pre-specified segmentation masks. The blue regions in the segmentation masks are predicted as bus, a randomly selected class.

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Conclusions

- Adversarial examples exist in both semantic segmentation and object detection
 - A simple algorithm based on gradient descent
 - The target can be arbitrary to some extents
- White-box attack: efficient and effective
- Black-box attack: a more challenging problem
 Transfer across datasets networks and tasks
 - Transfer across datasets, networks and tasks
 - Ensemble is an effective solution

Future Work

Defending adversarial attacks

– Attack vs. defense: which one is stronger?

- Finding out the reason of adversarial examples in the context of deep neural networks
- Integrating adversarial examples in training deep neural networks

Thank you!

Questions please?