#### **ICCV 2017**

# Adversarial Examples for Semantic Segmentation and Object Detection

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#### Outline

- Introduction
- Adversarial Examples in Computer Vision
- Dense Adversarial Generation (DAG)
- Experiments: White-box Attack
- Experiments: Black-box Attack
- Fancy Examples
- Conclusions and Future Work

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#### Introduction

- Deep Learning
  - The state-of-the-art machine learning theory
  - Using a cascade of many layers of non-linear neurons for feature extraction and transformation
  - Learning multiple levels of feature representation
    - Higher-level features are derived from lower-level features to form a hierarchical architecture
    - Multiple levels of representation correspond to different levels of abstraction

## Introduction (cont.)

- The Convolutional Neural Networks
  - A fundamental machine learning tool
  - Good performance in a wide range of problems in computer vision as well as other research areas
  - Evolutions in many real-world applications
  - Theory: a multi-layer, hierarchical network often has a larger capacity, also requires a larger amount of data to get trained

#### Outline

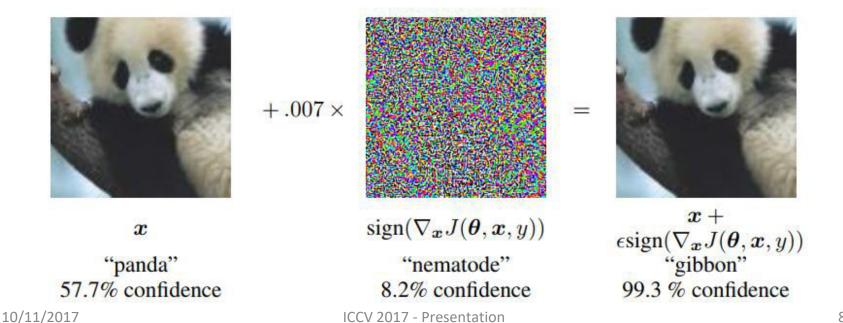
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## Adversarial Examples: Introduction

- What is an adversarial example (in this work)?
  - An image, with a small perturbation added, which can still be recognized by humans, but not by the computers (deep neural networks)
  - Type 1: an image with clear visual contents is recognized incorrectly
  - Type 2: an image with no visual contents is recognized as a non-understandable class

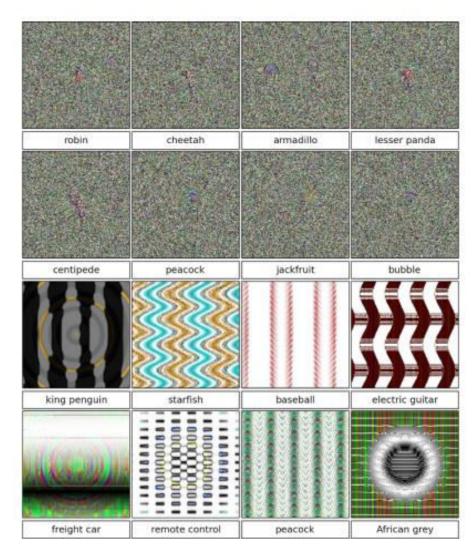
## Adversarial Examples: Type 1

- Slightly perturbed natural images that are completely wrongly recognized
  - Example from [Goodfellow, ICLR'15]



## Adversarial Examples: Type 2

- Meaningless patterns that are recognized as object classes with a very high confidence
  - Examples from [Nguyen, CVPR'14]



#### **Previous Work**

- Generating adversarial examples
  - Steepest gradient descent [Szegedy, ICLR'14], gradient sign [Goodfellow, ICLR'15], universal adversarial attack [M-Dezfooli, CVPR'17], etc.
- Defending adversarial examples
  - Distillation [Papernot, IEEE-SSP'16], large-scale learning [Kukarin, ICLR'17], ensemble [Tramer, arXiv'17], detection [Metzen, ICLR'17], randomization [Xie, arXiv'17], etc.

## Why Adversaries Exist?

- Opinion 1: deep networks are too complicated so that the high-dimensional space contains many non-linear or unexplainable structures, or they are too sensitive to small noise
- Opinion 2: deep networks are still too simple to defend these malignant attacks
- Opinion 3: deep networks are not the model we want!

#### **Our Contribution**

- We extend the adversarial examples to both semantic segmentation and object detection
  - We are the first to achieve this goal systematically
- We evaluated both white-box attack and black-box attack tasks
  - White-box: the network parameters are known
  - Black-box: the network parameters are unknown (transferring the adversarial perturbations)

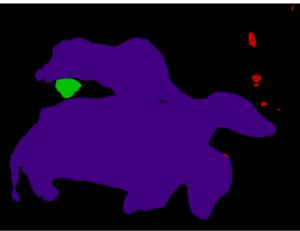
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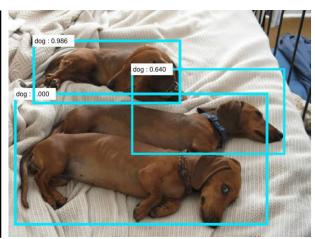
## Some Typical Results



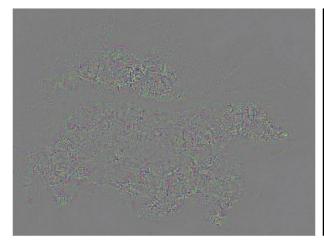
Original Image



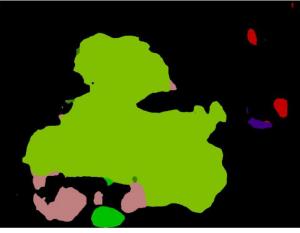
**Original Segmentation** 



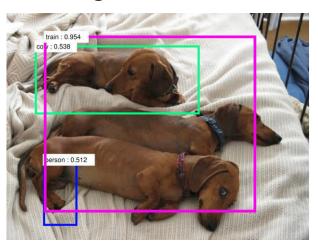
**Original Detection** 



Added Perturbation (10x)



**Attacked Segmentation** 



**Attacked Detection** 

## Formulation: Optimization Goal

- Let a deep network be  $f(X; \Theta) \in \mathbb{R}^C$ 
  - $\mathbf{X}$ : input region,  $\mathbf{\Theta}$ : weights (fixed), C: # of classes
- Goal: modifying X to make wrong prediction
- Optimization target: the basic unit
  - For classification: the entire image (previous work)
  - What about segmentation?
  - What about detection?

## Formulation: Optimization Goal

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  - $\mathbf{X}$ : input region,  $\mathbf{\Theta}$ : weights (fixed), C: # of classes
- Goal: modifying X to make wrong prediction
- Optimization target: the basic unit
  - For classification: the entire image (previous work)
  - For segmentation: all pixels in the image
  - For detection: densely distributed bounding boxes

#### Dense Adversarial Generation

- A white-box attack
  - Image and network dependent
- Flowchart
  - Defining the active set
  - Gradient descent
  - Until convergence

```
Algorithm 1: Dense Adversary Generation (DAG)
   Input: input image X;
                     the classifier \mathbf{f}(\cdot, \cdot) \in \mathbb{R}^C;
                     the target set \mathcal{T} = \{t_1, t_2, \dots, t_N\};
                     the original label set \mathcal{L} = \{l_1, l_2, \dots, l_N\};
                     the adversarial label set \mathcal{L}' = \{l'_1, l'_2, \dots, l'_N\};
                     the maximal iterations M_0:
   Output: the adversarial perturbation r;
1 \mathbf{X}_0 \leftarrow \mathbf{X}, \mathbf{r} \leftarrow \mathbf{0}, m \leftarrow 0, \mathcal{T}_0 \leftarrow \mathcal{T};
2 while m < M_0 and \mathcal{T}_m \neq \emptyset do
          \mathcal{T}_m = \{t_n \mid \arg\max_c \{f_c(\mathbf{X}_m, t_n)\} = l_n\};
            \sum_{t_n \in \mathcal{T}_m} \left[ \nabla_{\mathbf{X}_m} f_{l'_n}(\mathbf{X}_m, t_n) - \nabla_{\mathbf{X}_m} f_{l_n}(\mathbf{X}_m, t_n) \right];
       \mathbf{r}'_m \leftarrow \frac{\gamma}{\|\mathbf{r}_m\|_{\infty}} \mathbf{r}_m;
6 \mathbf{r} \leftarrow \mathbf{r} + \mathbf{r}'_m;
         \mathbf{X}_{m+1} \leftarrow \mathbf{X}_m + \mathbf{r}'_m;

m \leftarrow m+1;
   Return: r
```

## Comments on Object Detection

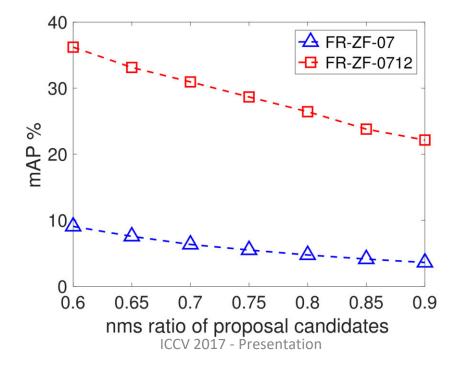
- We attacked a type of frameworks, which first extract a number of proposals, then assign a class label for each proposal
- A possibility: the adversarial perturbation changes the set of proposals, and our attack will not work on the new proposals
  - That is why we need to generate dense bounding boxes (see the next page)

## Diagnosis: Denseness

 Denseness: the number of generated boxes in object detection task (the more the better)

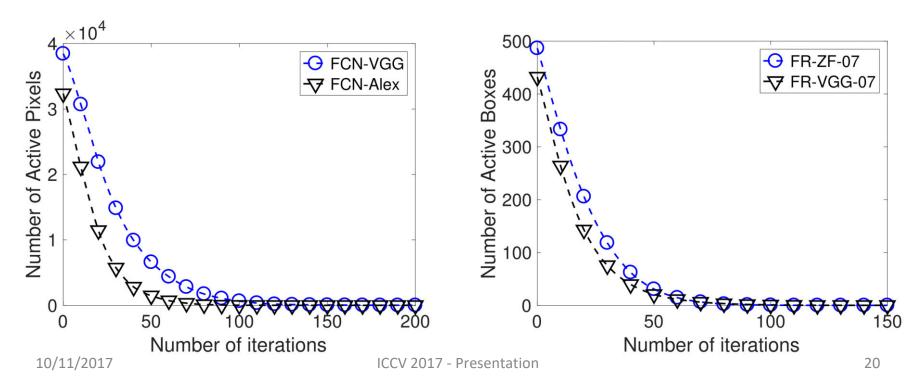
Controlled by the non-maximum-suppression

ratio



## Diagnosis: Convergence

- Convergence is mostly guaranteed
  - Failed to converge in a fixed # of rounds: < 1%
    - · Even in these cases, generated perturbations work well



## Diagnosis: Perceptibility

Low intensity of adversarial perturbations

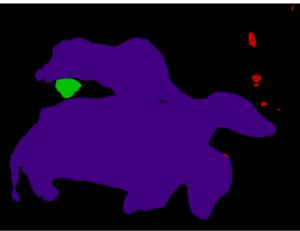
• Perceptibility: 
$$p = \left(\frac{1}{K}\sum_{k}||\mathbf{r}_{k}||_{2}^{2}\right)^{1/2}$$

- -K: # of image pixels
- $-\mathbf{r}_k$ : RGB vector of perturbation ([0,1]-normalized)
- Typical value of p is  $[1.0,3.0] \times 10^{-3}$

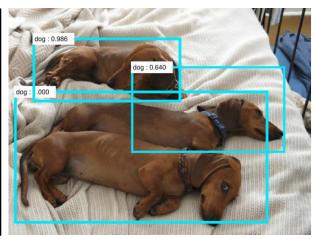
## Some Typical Results



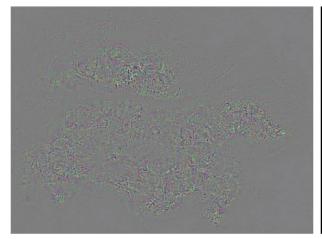
Original Image



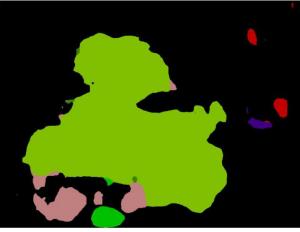
**Original Segmentation** 



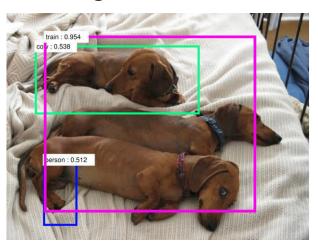
**Original Detection** 



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#### White-Box Attack: Definition

- Given an image X and a network  $f(X; \Theta)$  in which the structure and weights are known
  - This is the same setting as in the algorithm
  - Adversarial examples are easily generated, given that our algorithm converges (mostly guaranteed)

#### White-Box Attack: Results

- Semantic segmentation part
  - FCN and DeepLab were evaluated
  - Bold numbers indicate white-box attacks

Adversarial Perturbations from	FCN-Alex	FCN-Alex*	FCN-VGG	FCN-VGG*	DL-VGG	DL-RN101
None	48.04	48.92	65.49	67.09	70.72	76.11
FCN-Alex (r <sub>5</sub> )	3.98	7.94	64.82	66.54	70.18	75.45
FCN-Alex* (r <sub>6</sub> )	5.10	3.98	64.60	66.36	69.98	75.52
FCN-VGG (r <sub>7</sub> )	46.21	47.38	4.09	16.36	45.16	73.98
FCN-VGG* (r <sub>8</sub> )	46.10	47.21	12.72	4.18	46.33	73.76
$\mathbf{r}_5 + \mathbf{r}_7$	4.83	8.55	4.23	17.59	43.95	73.26
$\mathbf{r}_5 + \mathbf{r}_7$ (permuted)	48.03	48.90	65.47	67.09	70.69	76.04
$\mathbf{r}_6 + \mathbf{r}_8$	5.52	4.23	13.89	4.98	44.18	73.01
$\mathbf{r}_6 + \mathbf{r}_8$ (permuted)	48.03	48.90	65.47	67.05	70.69	76.05

#### White-Box Attack: Results

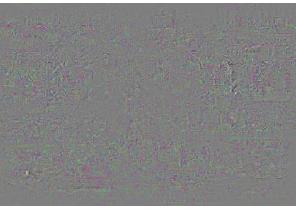
- Object recognition part
  - Faster-RCNN and R-FCN were evaluated
  - Bold numbers indicate white-box attacks

Adversarial	FR-ZF-07	FR-ZF-0712	FR-VGG-07	FR-VGG-	R-FCN-	R-FCN-
Perturbations from	F K-ZF-07	FK-ZF-0/12	FK-7 GG-07	0712	RN50	RN101
None	58.70	61.07	69.14	72.07	76.40	78.06
FR-ZF-07 $(\mathbf{r}_1)$	3.61	22.15	66.01	69.47	74.01	75.87
FR-ZF-0712 (r <sub>2</sub> )	13.14	1.95	64.61	68.17	72.29	74.68
FR-VGG-07 $(\mathbf{r}_3)$	56.41	59.31	5.92	48.05	72.84	74.79
FR-VGG-0712 (r <sub>4</sub> )	56.09	58.58	31.84	3.36	70.55	72.78
${f r}_1 + {f r}_3$	3.98	21.63	7.00	44.14	68.89	71.56
$\mathbf{r}_1 + \mathbf{r}_3$ (permuted)	58.30	61.08	68.63	71.82	76.34	77.71
$\mathbf{r}_2 + \mathbf{r}_4$	13.15	2.13	28.92	4.28	63.93	67.25
$\mathbf{r}_2 + \mathbf{r}_4$ (permuted)	58.51	61.09	68.68	71.78	76.23	77.71

### White-Box Attack: Examples



Original Image



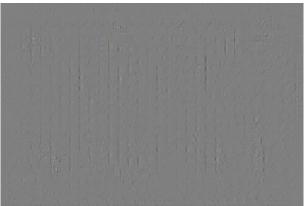
Added Perturbation (10x)



**Attacked Segmentation** 



Original Image



Added Perturbation (10x)



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#### Black-Box Attack: Definition

- Given an image X and a network  $f(X; \Theta)$  in which the structure and weights are *unknown* 
  - It is even possible that the task is unknown
  - This setting is much more challenging
  - The difficulty goes up with the difference between the source network (the white box) and the target network (the black box)

#### Black-Box Attack: Results

- Semantic segmentation part
  - Transfer across different training sets
  - Transfer across different networks

Adversarial Perturbations from	FCN-Alex	FCN-Alex*	FCN-VGG	FCN-VGG*	DL-VGG	DL-RN101
None	48.04	48.92	65.49	67.09	70.72	76.11
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#### Black-Box Attack: Results

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  - Transfer across different networks

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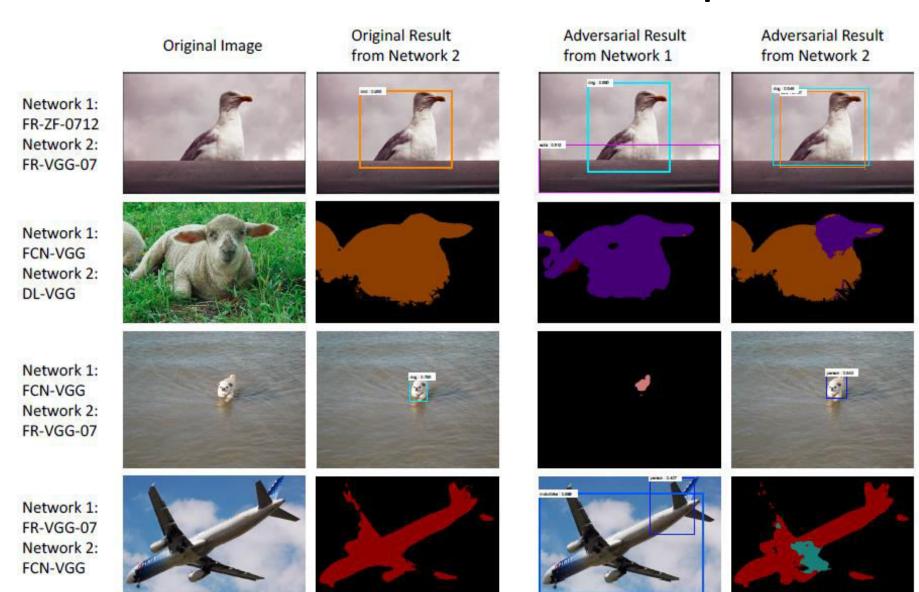
- Transfer across different tasks
  - This is the most challenging task investigated
  - Ensemble is the only way of enhancing attack

Adversarial	FR-ZF-07	FR-VGG-07	FCN-Alex	FCN-VGG	R-FCN-RN101	
Perturbations from	rk-Zr-0/	FK-VGG-0/	r CN-Alex	rcn-vgg	K-FCIN-KINIUI	
None	56.83	68.88	35.73	54.87	80.20	
FR-ZF-07 $(\mathbf{r}_1)$	5.14	66.63	31.74	51.94	76.00	
FR-VGG-07 (r <sub>3</sub> )	54.96	7.17	34.53	43.06	74.50	
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FCN-VGG (r <sub>7</sub> )	55.24	56.33	33.99	4.10	73.86	
${f r}_1 + {f r}_3 + {f r}_5$	5.02	8.75	4.32	37.90	69.07	
${f r}_1 + {f r}_3 + {f r}_7$	5.15	5.63	28.48	4.81	65.23	
${f r}_1 + {f r}_5 + {f r}_7$	5.14	47.52	4.37	5.20	68.51	
${f r}_3 + {f r}_5 + {f r}_7$	53.34	5.94	4.41	4.68	67.57	
$\mathbf{r}_1 + \mathbf{r}_3 + \mathbf{r}_5 + \mathbf{r}_7$	5.05	5.89	4.51	5.09	64.52	

#### Black-Box Attack: Facts

- Black-box attack is much more difficult
  - The difficulty goes up with the difference between the source and target networks
- "Difficulty levels" in transfer
  - Level 1: across different datasets
  - Level 2: across different network structures
    - Shallower networks are not easier to attack
  - Level 3: across different vision tasks
    - Same network structure makes things easier

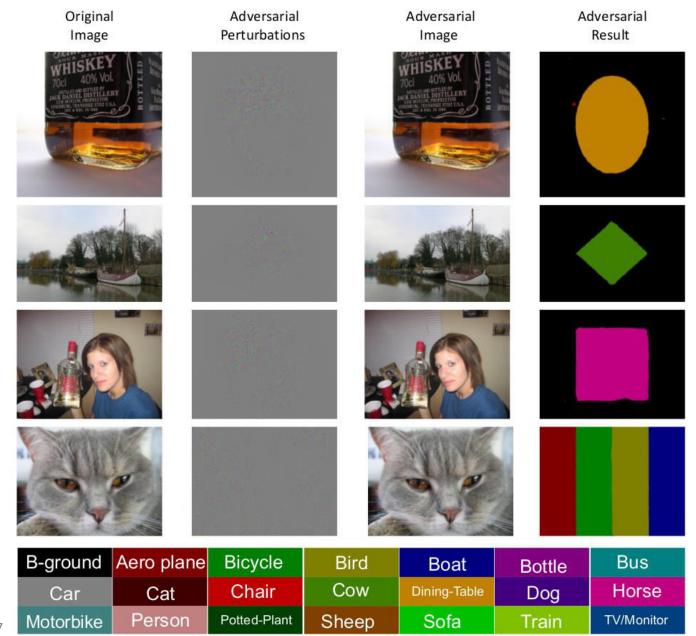
## Black-Box Attack: Examples



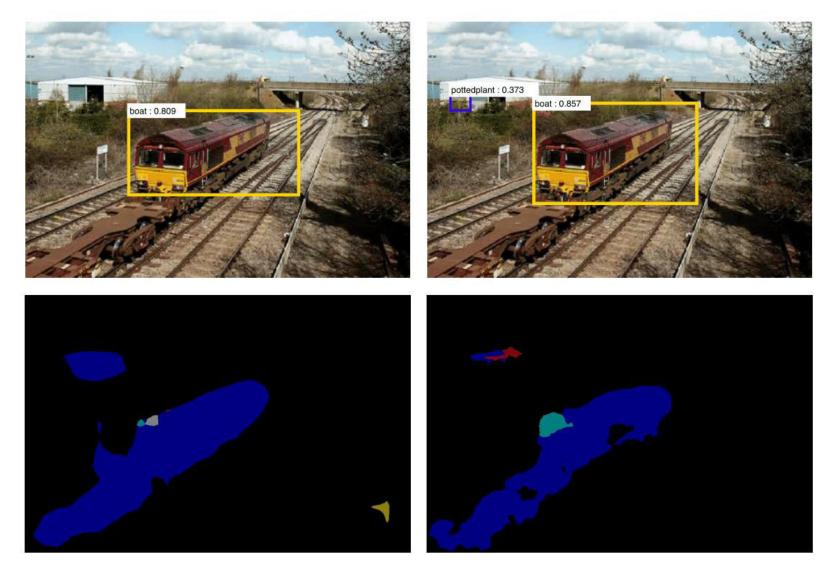
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#### Different Geometric Patterns



#### An adversarial example for both detection and segmentation



The top row shows FR-VGG-07 and FR-ZF-07 detection results, and the bottom row shows FCN-Alex and FCN-VGG segmentation results. The blue in segmentation results corresponds to boat.

#### Same adversarial example, Completely different Outputs



We add one adversarial perturbation (magnified by 10) to the same original image to generate different prespecified segmentation masks on two deep segmentation networks (FCN-Alex and FCN-VGG). This is a more difficult task compared to that shown in previous figure, where two different adversarial perturbations are used to generate two pre-specified segmentation masks. The blue regions in the segmentation masks are predicted as bus, a randomly selected class.

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#### Conclusions

- Adversarial examples exist in both semantic segmentation and object detection
  - A simple algorithm based on gradient descent
  - The target can be arbitrary to some extents
- White-box attack: efficient and effective
- Black-box attack: a more challenging problem
  - Transfer across datasets, networks and tasks
  - Ensemble is an effective solution

#### **Future Work**

- Defending adversarial attacks
  - Attack vs. defense: which one is stronger?
- Finding out the reason of adversarial examples in the context of deep neural networks
- Integrating adversarial examples in training deep neural networks

## Thank you!

Questions please?